

## Tracking Launch Vehicles in Interference and Jamming, Phase II

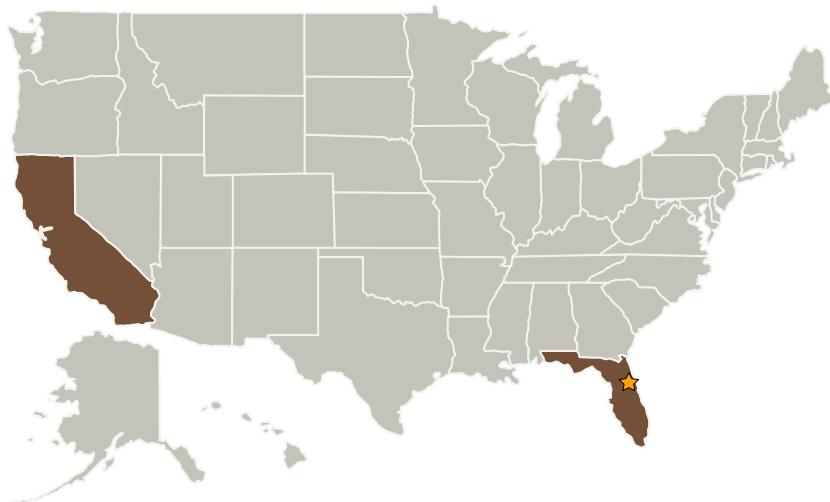
Completed Technology Project (2009 - 2012)



## Project Introduction

During the Phase I program, MARK Resources very successfully demonstrated the feasibility of using several distributed small and simple FRPAs that do not need to be precisely arranged, to suppress wideband interference and/or jamming and to provide sufficiently accurate and timely position and velocity measurements from the C/A code for launch vehicle range safety, antenna pointing, and attitude determination. The new technology, demonstrated via software simulation, is compatible with existing launch-capable GPS antennas and receiver hardware, and requires the addition of cabling and a common processor (and can accommodate channel mismatch in the receivers or added hardware). The processing load for jammer suppression is small, less than that for GPS signal tracking. The Phase I program employed signal simulation at the intermediate frequency (IF) of the receivers, after digitization. During Phase II, we propose to develop a demonstration unit consisting of launch-compatible antenna and receiver hardware plus processing software; and to measure its performance using a high-fidelity RF simulation.

## Primary U.S. Work Locations and Key Partners



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## Organizational Responsibility

### Responsible Mission Directorate:

Space Technology Mission Directorate (STMD)

### Lead Center / Facility:

Kennedy Space Center (KSC)

### Responsible Program:

Small Business Innovation Research/Small Business Tech Transfer

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Organizations Performing Work	Role	Type	Location
★ Kennedy Space Center(KSC)	Lead Organization	NASA Center	Kennedy Space Center, Florida
MARK Resources, Inc.	Supporting Organization	Industry	Torrance, California

Primary U.S. Work Locations	
California	Florida

## Project Transitions

**December 2009:** Project Start**March 2012:** Closed out

## Project Management

**Program Director:**

Jason L Kessler

**Program Manager:**

Carlos Torrez

## Technology Areas

**Primary:**

- TX17 Guidance, Navigation, and Control (GN&C)
  - └ TX17.4 Attitude Estimation Technologies
    - └ TX17.4.3 Attitude Estimation Sensors